

The Effect of the Quadriceps Angle on the Gait Pattern in Young Adults Aged 18-25 Years

18-25 Yaş Arası Genç Erişkinlerde Quadriceps Açısının Yürüme Paternine Etkisi

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ABSTRACT

Aim: The Quadriceps angle (Q angle) is used for the prediction, diagnosis, and follow-up of pathologies of knee joint. It gives information about the direction and size of forces applied to the patella. It is described as the angle formed by lines drawn from anterior superior iliac spine to the midpoint of the patella, and from the midpoint of the patella to tibial tuberosity. It gives information about the alignment of anatomical structures of the knee joint. We aimed to investigate the effects of Q angle upon gait and static balance.

Materials and Methods: A sample of 106 female and 105 male healthy subjects at age 18–25 years participated in our study. After notting their height and weight, bilateral Q angles were measured with goniometer in standing and supine positions. The force platform Zebris[©] FDM System Type FDM 1.5 and the WinFDM computer program were used for the gait and stance analysis. SPSS 20 program was used for statistical analysis of the obtained data. Statistical significance limit was determined as p<0.05.

Results: We assessed that there was no significant relationship between Q angle and gait analysis parameters. We observed that some of ground reaction force parameters and the butterfly diagram parameters obtained through the gait analysis as well as some of the stance analysis parameters were weak or moderately related to the Q angle. Parameters related to the Q angle did not show a pattern that would be classified by the Q angle measurement method or by the side or by the gender.

Conclusion: We think that it is necessary to conduct more extensive research in order to clarify the relationship between Q angle and walking pattern. We suggest that our research will contribute to the literature as a pioneering study in terms of the relationship between the Q angle and gait analysis as well as the stance analysis.

Keywords: Quadriceps angle, Q angle, gait analysis

ÖΖ

Amaç: Quadriceps açısı (Q açısı), patella'ya uygulanan çekim kuvvetlerin yönü ve büyüklüğü hakkında bilgi verdiğinden diz eklemini ilgilendiren patolojilerin öngörüsü, tanısı ve tedavi takibinde kullanılmaktadır. Spina iliaca anterior superior ile patella orta noktası arasındaki çizgi ve tuberositas tibiae ile patella orta noktası arasındaki çizgiler arasında ölçülür. Çalışmamızda diz ekleminin anatomik yapılarının dizilimi hakkında bilgi veren bu açı ile alt ekstremitenin önemli fonksiyon gösterdiği yürüme ve statik denge arasındaki ilişkiyi incelemeyi amaçladık.

Gereç ve Yöntem: Çalışmamıza katılan 18-25 yaş aralığında 106 kadın ve 105 erkek sağlıklı gönüllünün boy ve kilo ölçümü yapıldı, ayakta ve supin pozisyonlarda gonyometre ile bilateral Q açıları ölçüldü. Yürüyüş ve statik denge analizleri için kuvvet platformu Zebris[©] FDM System Type FDM 1,5 ve WinFDM bilgisayar programı kullanıldı. Elde edilen verilerin istatistiksel analizi için SPSS 20 programı kullanıldı. İstatistiksel olarak anlamlılık sınırı p<0,05 olarak belirlendi.

Bulgular: Yapılan değerlendirmeler neticesinde Q açısı ile yürüyüş analizi parametreleri arasında anlamlı ilişki olmadığı görüldü. Yürüyüş analizi yapılarak ulaşılan yer tepkime kuvvet parametreleri ve kelebek diyagramı parametreleri ile statik denge analizi parametrelerinden bazılarının Q açısı

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ile zayıf ya da orta düzeyde ilişkili olduğu görüldü. Q açısı ile ilişkili bulunan parametreler sağ veya sol tarafa, cinsiyete, Q açısı ölçüm yöntemine göre sınıflandırılabilecek bir düzen sergilemedi.

Sonuç: Q açısının yürüme paterni ile ilişkisinin aydınlatılması için kapsamlı araştırmalara ihtiyaç olduğunu ve araştırmamızın Q açısının, yürüme ve denge ile arasındaki ilişkiyi incelemesi açısından öncü bir çalışma olarak literatüre katkı sağlayacağını düşünüyoruz.

Anahtar Kelimeler: Quadriceps açısı, Q açısı, yürüyüş analizi

INTRODUCTION

The narrow angle formed between the line passing through the spina iliaca anterior superior (SIAS) and the midpoint of the patella and the line passing through the tibial tuberosity and the midpoint of the patella is called the Quadriceps angle (Q angle) (Figure 1)^{1,2}. Q angle represents the angle between the forces acting on the patella from proximal and distal directions³ and expresses the direction of the extension force applied to the patellar tendon^{1,2,4,5}.

The normal value range of the Q angle was found to be 10.14° in men and $15-23^{\circ}$ in women⁶. It has been said that differences in angle may be related to height and muscle strength⁷⁻¹⁰. Additionally, the Q angle is affected by the measurement position; values measured in the supine position were found to be 0.2-1.3° lower than those measured in the standing position¹⁰⁻¹³. In addition, contraction of the quadriceps femoris muscle during knee extension causes an increase in the Q angle by shifting the patella laterally, while when the knee is flexed, the Q angle decreases with the internal rotation of the tibia^{10,12,13}. It is known that the position of the foot during measurement also affects the Q angle².

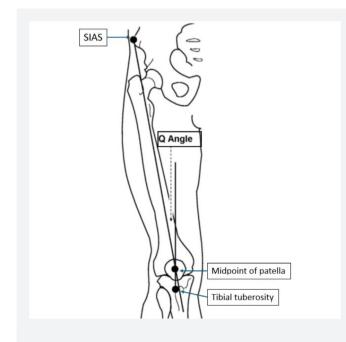


Figure 1. Quadriceps angle⁶ *SIAS: Spina iliaca anterior superior, Q angle: Quadriceps angle*

Increasing Q angle increases the pressure on the patellofemoral joint by increasing the lateral traction force applied to the patella¹⁴⁻¹⁶. Over time, this condition can cause patellofemoral pain and joint cartilage degeneration¹⁷⁻¹⁹.

However, the patellofemoral joint is an important part of knee joint biomechanics during walking. We think that keeping the patella in the correct position during knee extension and flexion may play an important role in the coordination of leg movements and the effective transfer of the forces produced by the lower extremity. The effect of this situation on walking can be examined using the gait analysis method because gait analysis offers the opportunity to objectively evaluate gait cycles using various measurement systems²⁰⁻²².

This study aims to fill an important gap in the existing literature by providing a detailed examination of the effect of the Q angle on walking mechanics. Studies to date have focused on static measurements of the Q angle and its relationship with patellofemoral pain or knee joint biomechanics^{1,2,14}. However, how the Q angle changes in dynamic processes, especially during walking, and the effects of these changes in different phases of the gait cycle have not been adequately investigated. By combining static Q angle measurements with dynamic gait analysis, this study may offer a new perspective in clinical evaluation and treatment protocols. In this way, the usability of Q angle measurement in the early diagnosis of individuals' gait disorders or knee joint pathologies can be increased.

MATERIALS AND METHODS

The number of volunteers to participate in the study was set as at least 86 for each group using the G*Power program (effect size: 0.5, alpha: 0.05, power: 0.9). A total of 211 healthy volunteers, including 105 men and 106 women between the ages of 18 and 25 years, participated in our study. The Ethics Committee approved this cross-sectional study for Scientific Research of the Faculty of Medicine of Trakya University, in accordance with the Declaration of Helsinki (decision no: 04/03, date: 01.03.2017). Those with acute or chronic diseases affecting the locomotor system were not included in the study. The same researcher recorded all measurements at the same time of the day (15:00-17:00). Volunteers were informed and then, their consent was obtained. Q angle was measured in standing and supine positions. While the subjects were standing, in an upright position and with their feet in neutral

position, the SIAS, patella midpoint and tuberositas tibiae were marked by palpation, and the narrow angle between the lines passing through these points was measured with a goniometer. During the measurement, the subjects were asked not to contract their quadriceps femoris muscle. Measurements were repeated three times with two-minute intervals for both sides and the average value was recorded. When measuring while standing, the fingertips were ensured to point straight ahead, and passive support was given to prevent foot rotation when measuring in the supine position.

Force platform Zebris[©], FDM System Type FDM 1.5 and WinFDM computer program were used to determine the walking pattern. Volunteers were asked to walk at their normal walking speed while standing upright, with their eyes open, their head

facing straight ahead, and their arms swinging freely at either side of the body. Gait analysis was repeated three times for each subject and average values were recorded. Data obtained through gait analysis were evaluated under the headings of time, space, time-phase and space-time^{20,21}. The parameters obtained as a result of gait analysis and used in our study are explained in Table 1.

Statistical Analysis

SPSS for Windows 20.0 was used to analyze the data obtained in the research. Since the Kolmogorov-Smirnov normality test showed that the data were in accordance with normal distribution, statistical analysis between groups was performed with the Student's t-test and results were expressed as

Table 1. Para	meters obtained by gait analys						
Time parameters	Step time (sec)	It is the time from the first contact of the foot on one side to the first contact of the foot with the ground on the other side. It is expressed as right step time and left step time.					
parameters	Double step time (sec)	It is the time between the first two consecutive ground contacts of the foot on the same side					
opace parameters	Stride length (cm)	It is the distance between the heels of two consecutive feet in the walking direction. The distance between two consecutive heels on the same side is called double stride length. A walking cycle includes steps on different sides that follow each other.					
	Step width (cm)	It is the distance between the vertical axes of the two sides. Vertical axes pass through the middle of the talocrural joint or calcaneus.					
	Foot rotation (°)	It is the angle measured between the walking direction and the long axis of the foot.					
Temporal/	Walking speed (cm/sec)	It is obtained by dividing the distance walked by the walking time. Double stride length can also be calculated by multiplying by cadence and dividing by two.					
spatial parameters	Cadence (tempo) (step/ minute)	It is the total number of steps taken in one minute.					
	Right-left stance (GC%)	The phase that begins with the first breaking of the heel of the foot onto the ground and continues until the toes of the same foot cease to contact the ground is called the stance phase. During a walking phase, weight is carried at this stage. The duration of this phase is referred to as the stopping time.					
	Right-left loading (GC%)	It is the ratio of the time elapsed during the stance phase until the first double support phabegins to the gait cycle.					
Time-phase parameters	Before right-left swing (GC%)	It is the phase from the first contact of the heel of the foot on one side to the ground until the toes of the foot on the other side are lifted off the ground.					
	Right-left swing phase (%GC)	It is the ratio of the time between the time when the toes leave the ground and the time when the heel of the same foot first touches the ground, to the entire cycle.					
	Right-left single support (%GC)	It is the phase in which only the foot on one side touches the ground. It is the phase that lasts from the last contact of the foot on the other side with the ground until the next fir contact of the toes of the same foot with the ground.					
	Total double support (%GC)	It is the sum of the two periods during which both feet touch the ground in a walking cycle.					
	Walking line length	When the ground contacts on both sides are examined separately, it is the average value of the line length showing the pressure centers of one side. It only shows the maximum peak pressure progression recorded in one side's steps. It is the only parameter that does not originate from the butterfly diagram screen.					
Butterfly diagram parameters	Single support line	It is the average length of the lines showing the progression of pressure by evaluating the entire contact of the soles of the feet with the ground.					
	Anteroposterior position	For all steps, it means that the intersection point of the pressure centers shifts forward and backward on the butterfly diagram screen.					
	Anteroposterior variability	It refers to the standard deviation value of the front-back position.					

GC: Gait cycle

mean \pm standard deviation. The Spearman's rank correlation test was performed to compare the relationship between Q angle and gait and balance parameters. The Spearman's rank correlation coefficient was evaluated as weakly correlated in the range of 0-0.24, moderately correlated in the range of 0.25-0.49, well correlated in the range of 0.50-0.74, and strongly correlated in the range of 0.75-1.00. A p-value<0.05 was considered statistically significant.

RESULTS

When the anthropometric data of the volunteers participating in our study were examined, it was seen that there was a significant difference (p<0.05) between the average height, body weight and body mass index of men and women, but there was no significant difference in the Q angle values. According to gait analysis data, among the parameters with a significant difference between genders, only the average value of cadence was higher in women (Table 2).

No significant relationship was detected between the volunteers' walking parameters and Q angle values (p>0.05) (Table 3).

No statistically significant relationship was found between the calculated Q angle mean values and ground reaction force (GRF) parameters in women (p>0.05). In men, there was a negative correlation between the mean Q angle values measured at both supine and standing positions on the left side and the F1 max of the right and the mean values of F1 max and F2 max of the left (p<0.05). It was observed that there was a negative correlation between the men's mean Q angle value measured while standing on the right and the mean F1 max value of the left (p<0.05) (Table 4).

		Female (n=106) mean ± SD	Male (n=105) mean ± SD	p-value
	Age (years)	19.23±1.34	19.38±1.42	0.418
	Height (cm)	164.62±5.64	179.19±5.96	0.0001
Anthropometric data	Weight (kg)	60.00±9.38	75.75±10.47	0.0001
	BMI (weight/heightx ²)	22.16±3.11	23.46±3.02	0.002
	Q supine R (°)	15.14±2.36	15.17 <u>+</u> 2.44	0.932
	Q supine L (°)	15.05±2.20	14.70±2.43	0.223
Q angle values	Q standing R (°)	15.51 <u>+</u> 2.27	15.42 <u>+</u> 2.56	0.486
	Q standing L (°)	15.37±2.21	15.02±2.52	0.184
	Left foot rotation (°)	6.23 <u>+</u> 4.12	10.86 <u>+</u> 4.77	0.0001 [*]
	Right foot rotation (°)	7.54 <u>+</u> 3.62	13.00±4.59	0.0001
	Step width (cm)	9.70 <u>+</u> 2.67	14.35 <u>+</u> 3.36	0.0001
	Left step length (cm)	61.34±5.21	63.44±6.70	0.026
	Right step length (cm)	61.43±5.24	64.07±6.37	0.003 [*]
	Double step length (cm)	122.60±10.13	127.10±12.80	0.012 [*]
	Left step time (sec)	0.86±0.35	0.94±0.23	0.041 [*]
	Right step time (sec)	0.91±0.29	0.96±0.19	0.102
	Double step time (sec)	1.00±0.00	2.27±12.98	0.315
	Left press phase (%)	62.50±1.73	62.84 <u>+</u> 1.52	0.107
Gait analysis parameters	Right press phase (%)	63.33±1.50	63.07±1.58	0.295
	Left loading (%)	12.92±1.33	12.85±1.47	0.823
	Right loading (%)	12.62±1.66	12.63±1.45	0.617
	Left single support (%)	36.97±1.56	37.36±1.59	0.120
	Right single support (%)	37.70±1.69	37.50±1.54	0.218
	Before left swing (%)	37.50±1.73	37.16±1.52	0.107
	Before right swing (%)	36.70±1.50	36.73±2.59	0.402
	Total double support (%)	25.71±3.94	25.25±2.75	0.868
	Cadence (steps/minute)	54.89 <u>+</u> 3.59	51.95±4.13	0.0001 [*]
	Speed (km/h)	3.96 <u>+</u> 0.55	3.96±0.68	0.815

Table 2. Continued		F L (- (- (-)		
		Female (n=106)	Male (n=105)	p-value
		mean ± SD	mean ± SD	
	F1 max R (N)	604.60±112.70	768.53 <u>+</u> 147.94	0.0001 [*]
	F1 max L (N)	628.93±112.90	800.10±148.33	0.0001
	F2 max R (N)	652.54±112.05	811.36±129.19	0.0001 [•]
	F2 max L (N)	666.26±107.49	824.82±127.17	0.0001
GRF parameters	T1 max R(sec)	0.19±0.07	0.20±0.051	0.3920
	T1 max L (sec)	0.19 <u>±</u> 0.04	0.20±0.05	0.5480
	T2 max R (sec)	0.51 <u>±</u> 0.06	0.54±0.052	0.0020*
	T2 max L (sec)	0.52±0.04	0.55±0.05	0.0001
	Walking line length L (mm)	211.82±13.33	233.31±18.69	0.0001
	Walking line length R (mm)	209.16±15.45	232.15±17.79	0.0001
Butterfly diagram parameters	Single support line L (mm)	132.53±16.19	141.77±14.55	0.0001
	Single support line R (mm)	133.02±13.41	141.73±14.78	0.0001
	Anteroposterior position (mm)	6.25±6.48	6.00±3.77	0.1780

Table 3. Correlation	on of	Q an	gle and gai	it analysis da	ita						
			Female (n:	=106) mean <u>-</u>	<u>F</u> SD		Male (n=105) mean ± SD				
Gait analysis parameters			Q supine R (°)	Q supine L (°)	Q standing R (°)	Q standing L (°)	Q supine R (°)	Q supine L (°)	Q standingR (°)	Q standing L (°)	
	L	r	-0.042	-0.099	-0.084	-0.105	-0.087	-0.140	-0.088	-0.094	
Fact votation (°)	L	р	0.667	0.313	0.393	0.283	0.377	0.153	0.374	0.341	
Foot rotation (°)	R	r	0.049	0.082	0.104	0.134	-0.008	0.005	0.068	0.051	
	n	р	0.617	0.403	0.289	0.169	0.937	0.960	0.491	0.604	
Step width (cm)		r	0.014	-0.002	-0.021	-0.027	-0.080	-0.088	-0.006	0.011	
		р	0.889	0.984	0.829	0.785	0.418	0.370	0.955	0.910	
	L	r	0.113	0.043	0.078	0.073	0.043	-0.024	-0.036	-0.067	
Ston Ionath (on)	Ľ	р	0.250	0.661	0.428	0.455	0.661	0.808	0.719	0.498	
Step length (cm)	R	r	0.131	0.074	0.086	0.093	0.036	-0.011	-0.005	-0.055	
		р	0.181	0.450	0.381	0.342	0.712	0.909	0.963	0.578	
Double step length		r	0.121	0.058	0.083	0.083	0.054	0.004	-0.009	-0.041	
(cm)		р	0.215	0.558	0.397	0.399	0.588	0.970	0.930	0.681	
		r	-0.071	-0.056	-0.061	-0.062	0.009	0.035	0.026	0.103	
Step time	L	р	0.467	0.570	0.532	0.526	0.928	0.719	0.792	0.298	
(sec)	R	r	-0.033	-0.089	-0.126	-0.123	0.092	0.084	0.051	0.102	
	n	р	0.736	0.364	0.198	0.210	0.350	0.392	0.608	0.301	
Double ston time (r	-0.049	-0.024	-0.048	-0.051	0.067	0.077	0.055	0.100	
Double step time (s	eej	р	0.620	0.805	0.524	0.605	0.498	0.434	0.578	0.308	
	L	r	0.104	0.086	0.157	0.130	-0.055	-0.047	-0.033	-0.014	
Stance	L	р	0.288	0.382	0.109	0.182	0.579	0.636	0.741	0.887	
phase (%)	R	r	-0.047	0.011	-0.032	-0.007	0.006	0.015	0.002	0.082	
	n	р	0.630	0.909	0.741	0.945	0.951	0.876	0.983	0.407	

			Female (n:	=106) mean <u>-</u>	<u>t</u> SD		Male (n=105) mean ± SD				
Gait analysis parameters			Q supine R (°)	Q supine L (°)	Q standing R (°)	Q standing L (°)	Q supine R (°)	Q supine L (°)	Q standingR (°)	Q standing L (°)	
	L	r	-0.033	-0.005	0.015	0.021	0.051	0.044	0.043	0.101	
Loading (%)	L	р	0.735	0.962	0.877	0.835	0.607	0.659	0.664	0.307	
	R	r	0.094	0.110	0.137	0.154	-0.092	-0.088	-0.085	-0.027	
	n	р	0.336	0.261	0.162	0.116	0.350	0.373	0.387	0.82	
	L R	r	0.015	-0.037	-0.018	-0.052	-0.068	-0.060	-0.046	-0.124	
Single support		р	0.877	0.703	0.852	0.596	0.492	0.544	0.643	0.207	
(%)		r	-0.054	-0.041	-0.085	-0.093	0.065	0.071	0.028	0.005	
		р	0.583	0.675	0.389	0.341	0.510	0.470	0.778	0.957	
	L	r	-0.104	-0.086	-0.157	-0.130	0.055	0.047	0.033	0.014	
Before swing (%)		р	0.288	0.382	0.109	0.182	0.579	0.636	0.741	0.887	
Defore swing (%)	R	r	0.043	-0.017	0.025	0.001	-0.007	-0.014	-0.004	-0.080	
	n	р	0.662	0.866	0.799	0.994	0.947	0.889	0.964	0.415	
Total double suppo	rt	r	0.063	0.101	0.108	0.120	-0.014	-0.030	-0.014	0.038	
(%)		р	0.522	0.301	0.272	0.221	0.887	0.764	0.884	0.699	
Cadence (steps/min	uite)	r	0.046	0.026	0.048	0.056	-0.075	-0.088	-0.054	-0.102	
caucie (steps/iiiii	utej	р	0.639	0.792	0.624	0.566	0.447	0.374	0.582	0.300	
Speed (km/h)		r	0.089	0.008	0.066	0.050	-0.059	-0.057	-0.089	-0.129	
Speed (kiii/ii)		р	0.365	0.938	0.502	0.614	0.551	0.565	0.368	0.190	

correlated, Q: Quadriceps angle

			Female (n=	106) mean	± SD		Male (n=105) mean ± SD				
GRF paramete	rs		Q supine R (°)	Q supine L (°)	Q standing R (°)	Q standing L (°)	Q supine R (°)	Q supine L (°)	Q standing R (°)	Q standing L (°)	
	R	r	0.139	0.138	0.128	0.122	-0.174	-0.254	-0.139	-0.222	
F1 max (N)	ĸ	р	0.155	0.159	0.190	0.212	0.076	0.009*	0.159	0.023*	
	L	r	0.065	0.044	0.031	0.033	-0.182	-0.271	-0.228	-0.268	
	L	р	0.507	0.651	0.752	0.737	0.062	0.005*	0.019	0.006*	
	R	r	0.127	0.121	0.111	0.127	-0.061	-0.157	-0.62	-0.136	
[2	n	р	0.196	0.215	0.257	0.193	0.539	0.110	0.528	0.166	
F2 max (N)	L	r	0.027	0.017	0.003	0.034	-0.106	-0.212	-0.145	-0.211	
	L	р	0.785	0.862	0.979	0.733	0.280	0.030*	0.141	0.031*	
	R	r	-0.057	-0.032	-0.054	-0.063	0.030	0.057	0.018	0.052	
T1 may (cm)	n	р	0.560	0.747	0.581	0.520	0.760	0.566	0.858	0.601	
T1 max (sn)	L	r	0.001	-0.024	-0.036	-0.050	0.031	0.035	0.045	0.092	
	L	р	0.991	0.809	0.714	0.612	0.752	0.719	0.649	0.352	
	R	r	0.045	0.056	0.067	0.038	0.065	0.074	0.039	0.087	
T2 max (sn)	n	р	0.647	0.569	0.496	0.696	0.507	0.452	0.691	0.380	
		r	-0.021	0.015	-0.002	0.011	0.151	0.152	0.150	0.180	
	L	р	0.834	0.878	0.986	0.913	0.124	0.121	0.127	0.066	

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In women, a weak correlation was observed between the mean value of the Q angle on the right knee and the length of the walking line on the right side and the single support line on the left side (r=0-0.24, p<0.05). It was observed that there was a weak correlation between the mean Q angle value measured while standing on the left knee and the length of the left walking line, the length of the right walking line and the left support line (r=0-0.24, p<0.05). In men, the mean Q angle values measured in the supine position were weakly related to the anteroposterior position in both knees (r=0-0.24; p<0.05). The mean Q angle values obtained from standing measurements were found to be moderately correlated (r=0.25-0.49; p<0.05) (Table 5).

DISCUSSION

All parts of the lower extremity take part in ensuring movement and maintaining balance by performing a series of functions together and sequentially during walking. The knee joint is affected biomechanically and kinematically by the placement and alignment of other locomotor system structures of the lower extremity^{3,23}. The fact that the Q angle is higher than the normal value range stated in the literature is associated with the dysfunction of the extension mechanism of the quadriceps femoris muscle and the lateral malposition of the patella and constitutes the basis for patellofemoral pain¹⁶. It has been suggested that the increased anteversion angle of the femur or the internal rotation of the tibia causes the Q angle to increase, and the internal rotation of the tibia may be compensated by the eversion of the subtalar joint²⁴. Individuals with a wider Q angle may have a wider angle of eversion at the level of the subtalar joint, which can lead to lateral displacement of the patella²⁵.

As a result of their measurements using the traditional method, Aglietti et al. ²⁶ found the average value of the Q

angle to be 15° and suggested that values above 20° were outside the normal. Kernozek and Greer²³ measured average Q angle as 16.63±6.07° while the subjects were standing in their preferred position, and 14.57±8.06° when the heels were 4 cm apart and the feet were abducted 7°. Stating that the Q angle is in the range of 8-17° according to literature data and that the angle is wider in women, Woodland and Francis12 also stated in their study that the Q angle measured in the standing position is 0.9-1.2° higher than in the supine position. They suggested that this situation might be related to the load carried while standing¹². Guerra et al.¹¹ suggested that there was no significant difference between the Q angle measured at supine and standing positions, but that the Q angle narrowed significantly when the quadriceps femoris muscle contracted, and this was due to the external and upward displacement of the patella.

In the study by Horton and Hall⁷, the average Q angle value was found to be $13.5\pm4.5^{\circ}$, and the average Q angle value of women was 4.6° higher than that of men. They stated that there was no relationship between hip width and femur length and Q angle, regardless of gender factor. However, no information was given about whether the quadriceps femoris muscle was contracted or not and the foot position during the measurement.

There are studies in the literature suggesting that women have wider Ω angles^{11,12,16,26}. However, Grelsamer et al.⁸ suggested that the Ω angle varied depending on height, not gender, and that there was no difference between genders when the distance between the two SIAS for pelvic width was measured. In that study, Ω angles were measured only on the right knee in the supine position, with the knees flexed at 10°, and no information was given about the clinical conditions of the subjects.

Table 5. Correlation of the quadriceps angle and butterfly diagram data										
			Female (n	=106) mea	n ± SD		Male (n=105) mean ± SD			
Butterfly diagram paramet	Q supine R (°)	Q supine L (°)	Q standing R (°)	Q standing L (°)	Q supine R (°)	Q supine L (°)	Q standing R (°)	Q standing L (°)		
		r	0.135	0.108	0.178	0.198	-0.007	-0.065	-0.025	-0.094
Walking line length	L	р	0.166	0.268	0.068	0.041*	0.945	0.512	0.801	0.339
(mm)	R	r	0.201	0.161	0.233	0.238	0.022	-0.046	0.002	-0.035
	n	р	0.039*	0.099	0.016*	0.014*	0.822	0.643	0.986	0.724
	L	r	0.223	0.158	0.228	0.192	-0.008	-0.026	0.044	-0.062
Single compart line (mm)		р	0.022*	0.106	0.019*	0.048*	0.933	0.796	0.659	0.531
Single support line (mm)	D	r	0.162	0.099	0.158	0.122	0.083	0.054	0.099	0.026
	R	р	0.096	0.315	0.106	0.213	0.402	0.581	0.315	0.793
r r		0.077	0.077	0.188	0.080	0.140	0.230	0.213	0.256	
Anteroposterior position (mm)			0.433	0.433	0.053	0.414	0.153	0.018*	0.029*	0.008*
Spearman correlation, R: Right, L:	Left, S	SD: Stand	lard deviation,	r: Spearman	correlation coeffi	cient; 0-0.24 wea	kly, 0.25-0.49	moderately, 0.5	0-0.74 well, 0.75	-1.00 strongly

Spearman correlation, R: Right, L: Left, SD: Standard deviation, r: Spearman correlation coefficient; 0-0.24 weakly, 0.25-0.49 moderately, 0.50-0.74 well, 0.75-1.00 strongly correlated, *= p<0.05

There are studies supporting that individuals who lead an active life have a narrower Q angle. It has been suggested that increased sports activity affects the contraction power of the quadriceps femoris muscle, causing the Q angle to narrow^{27,28}.

In our study, although there was a significant difference between the heights of the volunteers according to gender and the average Q angle values of women were higher than men, there was no significant difference in the average Q angle values between genders. In this respect, the results of our study differ from literature indicating that the average Q angle values of women are significantly higher than men. This difference may be due to the difference in the Q angle measurement method. We think that examination of other anatomical and anthropometric measurements of the lower extremity, such as pelvic width and the distance between SIAS and tibial tuberosity, may contribute positively to the evaluation.

In our study, the average value of the Q angle increased between 0.32 and 0.48 when moving from the supine position to the standing position. In this respect, our findings are compatible with literature information stating that the Q angle is wider in the supine position. The fact that the increase in angle value was not as high as in Woodland and Francis¹² study may be related to the importance given to foot position in our measurements. In addition, the sample group in that study was selected from students receiving regular physical education. The sports habits of the volunteers participating in our study were not questioned.

In a study examining the relationship between hindfoot movement and Q angle in the stance phase of walking, it was found that there was a weak relationship between statically and dynamically measured Q angle and hindfoot movement. It has been said that walking with larger Q angle values is not associated with a larger eversion angle or hindfoot movement in the stance phase²³.

In our study, it was observed that there was no significant relationship between Q angle measurements and gait analysis data in both genders. When GRF parameters and Q angle data are compared, the lack of a relationship between F1 max and F2 max values of women may be related to the fact that these values are significantly lower than those of men. T1 max and T2 max values were not found to be related to Q angle in either gender.

Study Limitations

According to the data we obtained, it was observed that the average values of the Q angle were compatible with the values obtained using a similar measurement method, but did not show a significant difference between genders^{11,12,16,26}. While there is no significant relationship between Q angle and gait analysis parameters in healthy young individuals, it was observed that there was a weak or moderately significant relationship with some of the GRF parameters and butterfly diagram parameters. At this point, the fact that our sample group consisted of healthy young adults and the mean values of the Q angle were within the normal range emerged as a limiting factor in terms of the generalizability of the results to different age groups and clinical situations. Another factor that limits our study is the Q angle measurement method because the use of a manual goniometer may negatively affect the objectivity of the data.

CONCLUSION

This study aimed to fill an important gap in the literature by evaluating the effects of Q angle on walking mechanics. The lack of a significant relationship between Q angle and gait analysis parameters in the sample of healthy young individuals indicates that the effects of Q angle on the gait cycle may be limited. However, it is clear that gender differences, physical activity level and dynamic processes need to be examined in a larger sample and with more sensitive methods. The findings of this study provide a new perspective on the usability of the Q angle in early diagnosis and treatment planning and serve as an important reference for future research.

Ethics

Ethics Committee Approval: The Ethics Committee approved this cross-sectional study for Scientific Research of the Faculty of Medicine of Trakya University, in accordance with the Declaration of Helsinki (decision no: 04/03, date: 01.03.2017).

Informed Consent: Volunteers were informed and then, their consent was obtained.

Footnotes

Authorship Contributions

Concept: O.T., E.U., Design: A.Z.Y.K., O.T., E.U., Data Collection or Processing: A.Z.Y.K., Analysis or Interpretation: A.Z.Y.K., O.T., E.U., Literature Search: A.Z.Y.K., E.U., Writing: A.Z.Y.K., O.T., E.U.

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